



CENTRAL FLORIDA TSM&O CONSORTIUM MEETING SUMMARY

Meeting Date: March 3, 2022 (Thursday) Time: 10:00 AM – 12:00 PM

Subject: TSM&O Consortium Meeting

Meeting Location: Teleconference

FDOT RTMC 4975 Wilson Rd. Sanford, FL 32771

I. OVERVIEW

The purpose of this recurring meeting is to provide an opportunity for District Five FDOT staff and local/regional agency partners to collaborate on the state of the TSM&O Program and ongoing efforts in Central Florida. Jeremy Dilmore gave a short introduction and outlined the meeting agenda.

I. I-4 EXPRESS LANES

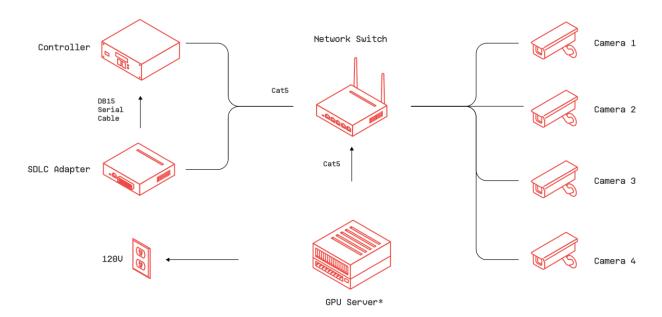
Jeremy Dilmore gave a short introduction and briefly discussed the I-4 Express Lanes.

- I-4 Express Lanes are now tolling at \$0.50 per segment
- will look at volumes now
- 10,000 vehicles per day so far
- developing SOGs for ramp metering effort
 - o not looking to deploy during event management yet; may change
 - o working with Lynx on holding greens for buses to help them keep their speeds up the ramps

II. CURRUX VISION AI - TAKEAWAYS

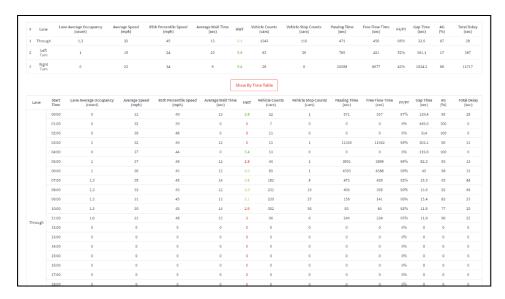
Hazem El Assar (Orange County) described Orange County's experience, lessons learned, and takeaways from their Currux Vision intersection deployment.

- Use Case Examples:
 - o 95%+ accurate big data collection and analytics
 - o traffic safety / near miss detection
 - o detecting traffic violations
 - o NTCIP/SDLC detection and adaptive control (including ped and bike detection)
- Currux Vision System Components
 - "Brain" Smart City Al-Vision Computer Vision Al System for Smart Cities based on NVIDIA GPU multi-core processors (Linux OS), with wide temperature operating range and resistance to shock/vibration
 - o System Architecture



- Currux Vision works with any existing or new camera system
- Functionality
 - o SDLC Detection unlimited number of dection zones; SDLC calls can be placed from the cabinet or remotely
 - Advanced Traffic Analytics Reports
 - Lane Occupancy
 - Counts with classification
 - Counts and speed by lane
 - Wait times
 - Average speed by lane
 - Total delay

- 85th percentile speed by lane
- Passing time
- Free flow/passing time ratio
- Time gap
- Arrivals on green

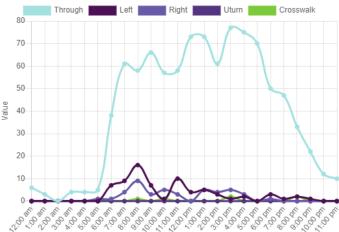


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- o Real-time notifications with photo evidence
- Intersection Adaptive / Green Utilization
 - o Single intersection or corridor level adaptive system using data collected by Currux Vision
 - o model can be trained on data for the previous day/week/month
 - o automatically calculates intersection split times in under 30 seconds to reduce the total delay at the intersection
 - o differentiates between week/weekend
 - o weighting applied to various approaches
 - o system recommends the new split times or automatically upload the calculated split times to the controller using NTCIP
- Turn Count Analytics
 - Vehicle counts by turn type and class
 - o 5 to 60 minutes time bins
 - o Ped and bike counts in crosswalk
 - o PDF & Excel reports export
- Pedestrian Detection & Tracking
 - Track in any direction
 - o accurate counts
 - o PED speed
 - o red extension
 - o passive ped detection





- Other features
 - Existing detection auditing missed/false calls
 - o Red light runner detection

Discussion:

- Q: Rich Ataman Where are the videos stored?
 - o A: Hazem On the device itself.

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- Q: Rich How does that work with public records?
 - o A: We don't retain the video outside the device itself.
- Q: If you moved into this long-term, would you develop a more long-term retention plan?
 - o A: Yes.
- Q: Does it adjust left turn?
 - o A: It does not make any recommendations, it just provides data
- Q: Bryan Homayouni Does it make predictive analytics?
 - o A: Only in real time; not over long timeframe.
- Q: Bryan How long was the pilot?
 - o A: 2 months.
- Q: Bryan What is your confidence in the system?
 - o A: confirmed their claim of 95% accuracy
 - can't really say what level of accuracy it has on false alerts
 - Jeremy trying to determine a metric/system to verify accuracy of system; setting up test with UCF
 - o need to develop a minimal accuracy threshold
 - o near-miss has promise for arterial & freeway
 - o if we're using good underlying data, it has a lot of use cases
- Q: Bryan is there a list of vendors being tested?
 - o A: Bosch, InNovo, Currux, Derq
- Q: Nabil Muhaisen is 5-minute interval the shortest option?
 - o A: Most likely
 - o Jeremy -
 - Iteris can do 15 minutes
 - Gridsmart 1 minute
 - Miovision 1 minute
 - InNovo 1 minute
 - o use 1-minute intervals for predictive analytics
- Q: Aware of any other regions using this system?
 - o extensively in California; contract with D7
- Q: Are we going to complement the system with anything?
 - o cannot replace existing systems because its not approved by TERL; supplementing standard systems
- Q: Only on fixed focal camera? Not 360° camera?
 - o Must be fixed camera; 1 per approach

III. CFMPOA TSMO NETWORK

Eric Hill briefly discussed the latest coordination with the Central Florida MPO Alliance (CFMPOA) regarding *TSMO Regional Projects*.

- Regional TSMO project impacts two contiguous cities/counties
- Set of integrated strategies to optimize the performance of operations on existing/new infrastructure

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- Serves regional transportation needs such as access to and from the area outside the region
 - o freight service and parking; evacuation; security and privacy
- Some caveats
 - o Problem statement
 - o MPOs/TPOs may not have projects that meet the working definition
 - o TSMO is a dynamic discipline
 - o Low technology to High technology
- Presented TSMO Regional Project definition to CFMPOA in February; received concurrence
- Potential examples
 - SR 40 Rural Signalized Intersections Collison Warning System (SR 40 through Volusia and Marion Counties)
 - o Beach Parking Information System (Flagler, Volusia, Brevard)
- Next Steps
 - o FDOT Support
 - o Prioritization
 - Advisory Team
 - o Coordination with FDOT D1 (Polk TPO)

IV. DRONE WORKSHOP

Eric Hill gave a brief explanation of the upcoming Drone Workshop at the RTMC.

- Eric has been working with Sheryl to determine how drones are used in transportation
- will hold a workshop on March 31
 - o half day at RTMC
 - o half of meeting will be classroom style; other half will be live demo
- will send out an email for a survey and for more information

V. CONSIDERATIONS AND APPLICATIONS FOR INTEGRATING CAVINTO COMPLETE STREETS.

David Williams provided a brief summary of the *Considerations and Applications for Integrating CAV into Complete Streets* technical memo published by FDOT Central Office.

- Complete Street prioritizes travel and safety for all users of the right-of-way, regardless of mode
- Two primary topics in the Technical Memo:
 - o Complete Streets Planning Considerations for CAV
 - o Applications of CAV technology to enhance Complete Streets
- Complete Streets Planning Considerations
 - o Emerging modes of travel may affect Complete Streets
 - o Curb management
 - o Impacts on parking
 - Land use considerations
- Applications of CAV to enhance Complete Streets

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- o Infrastructure-based strategies
- o Vehicle-based strategies
- o Bike/Ped/Micro-based strategies
- Next Steps beyond the white paper
 - o Identify crossovers between CAV and Complete Streets programs
 - o Develop CAV/Complete Streets toolbox for practitioners
 - o Conduct CAV/Complete Streets training webinar for FDOT staff and consultants
 - Identify opportunities for pilot project(s)

VI. TAKING TIME TO FLEX

Garrett Popovich briefly discussed the TSMO eLearning platform FLEX.

- What's new?
 - o Updated design
 - o New courses available
 - ITS Fiber Design
 - RTMC Phone System
 - BlueToad/BlueARGUSTraining
 - RICMS Response Plan Training
 - o Active Users 318
 - o Courses completed 231
 - o Most popular
- Upcoming courses
 - o Adaptive Signal Control Technology (ASCT) Training
 - o ITS CEI Dynamic Message Sign
 - o ITS CEI Road Weather Information System
 - o Manual on Uniform Traffic Studies (MUTS)

VII. STROZ PROJECT UPDATE

Jeremy Dilmore gave an update on the Signal Training for Regional Optimization Zone (STROZ) traffic signal training site at the RTMC.

- STROZ is a fully equipped training site located at the RTMC
- Purpose to provide a real-world scenario for training, demonstrations, and testing to occur
- The STROZ platform will enable FDOT to:
 - Host hands-on training for local agency staff (signal technicians)
 - Host vendors so they can demonstrate new technologies



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- o Teach best practices for maintenance, repairs, and troubleshooting
- Status
 - o 90% of infrastructure is completed and installed
 - o Remaining work includes installation of various roadside devices
 - o Target completion end of March 2022
 - o Updated design

VIII. CURRENT INITIATIVES

Jeremy Dilmore briefly provided an update on the current work efforts throughout District Five.

- PedSafe Construction mostly completed
- Kiosks at UCF isntalled and will be tested on 3/10
- AV Shuttle commissioned both routes; power issue affected one
- Event Management hoping to finish integration/testing soon
- I4 FRAME plans completed
- TAPS-LA Osceola RFP completed; ad through Osceola in February
- Orlando AID SODA TOP in procurement now
- Maintenance Contract currently in Procurement
- ATTAIN
 - o switched from Siemens to Intelight
 - would that include ASCT
 - there were plans for some updates, but not sure detection/adaptive was a part of it
 - it was intended to just be IMCs, not necessarily detection
- If anyone has issues with hardware/contractors, please let us know

IX. NEXT MEETING

May 19, 2022

X. ATTACHMENTS

- A Presentation Slides
- B Meeting agenda

END OF SUMMARY

This summary was prepared by David Williams and is provided as a summary (not verbatim) for use by the Consortium Members. The comments do not reflect FDOT's concurrence. Please review and send comments via e-mail to dwilliams@vhb.com so the meeting summary can be finalized.

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Welcome to the TSM&O Consortium Meeting March 3, 2022





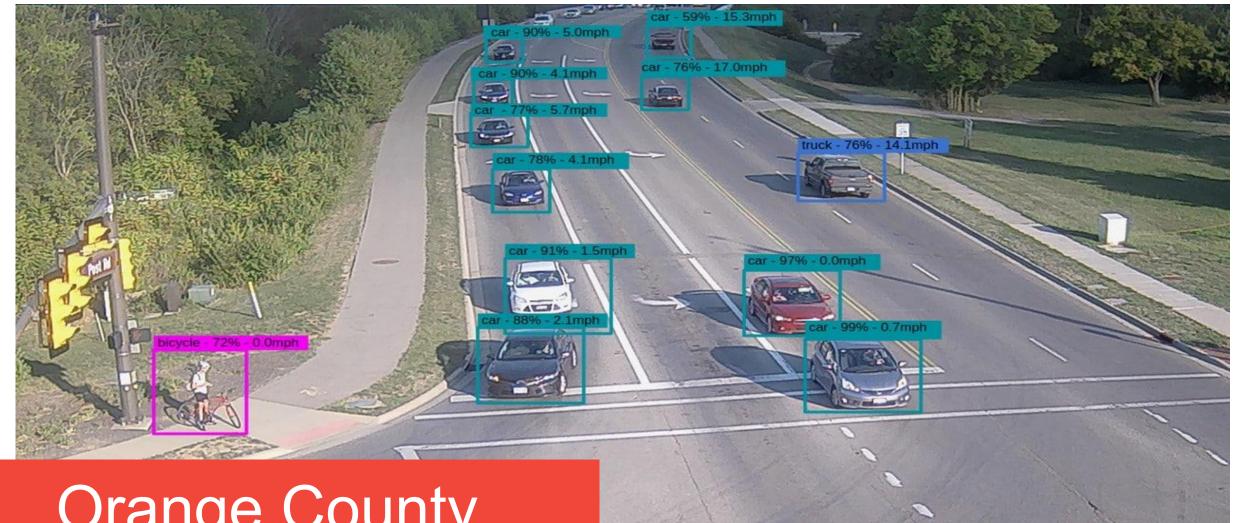


Meeting Agenda

- 1. Welcome
- 2. Currux Vision Al
- 3. Regional TSM&O Prioritized Projects
- 4. Drone Workshop Information
- 5. Integrating CAV into Complete Streets
- 6. Taking Time to FLEX What's New in Training
- 7. STROZ Training Platform Update
- 8. Current Initiatives





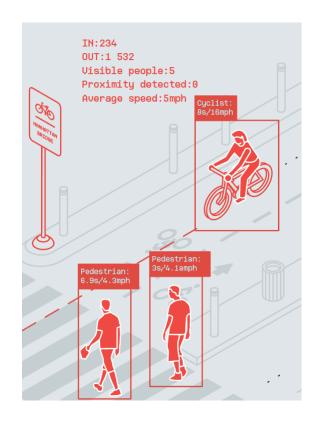


Orange County

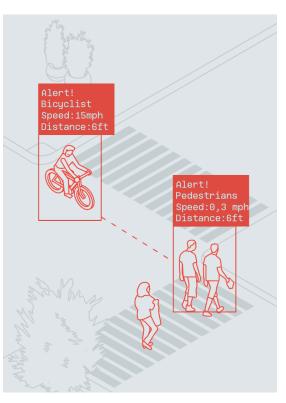
Artificial Intelligence for Intersections

Based on Currux Vision Data

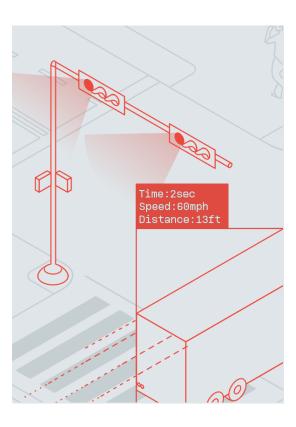
Example of Use Cases:



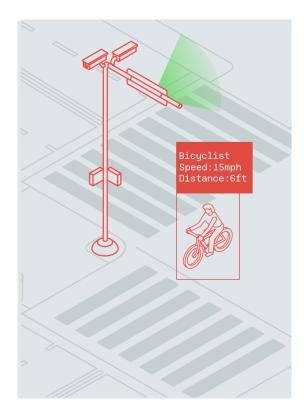
95%+ accurate big data collection and analytics



Traffic Safety / Near Miss Detection



Detecting traffic violations



NTCIP/SDLC Detection and Adaptive (including Ped and Bike detection)

The Brain

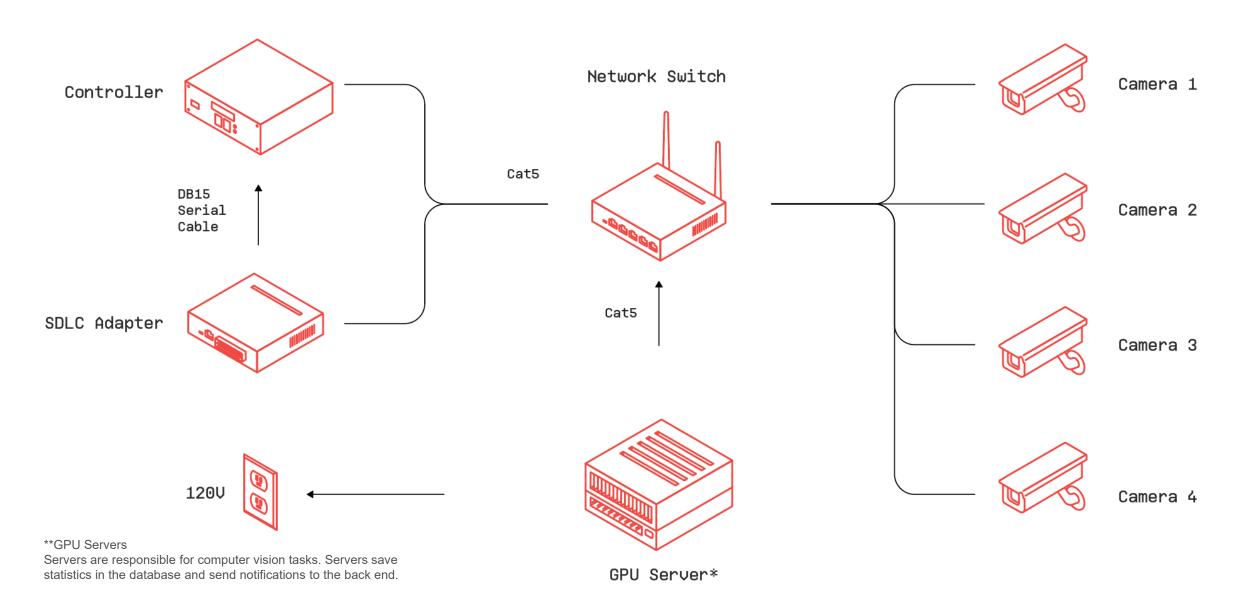
SMART CITY AI-VISION Computer Vision AI System for Smart Cities

- Based on NVDIA GPU Multi Core Processors
- Linux Operating System
- Small Size 4.1" x 4.1" x 2.5"
- Wide temperature operating range and resistance to shock and vibration

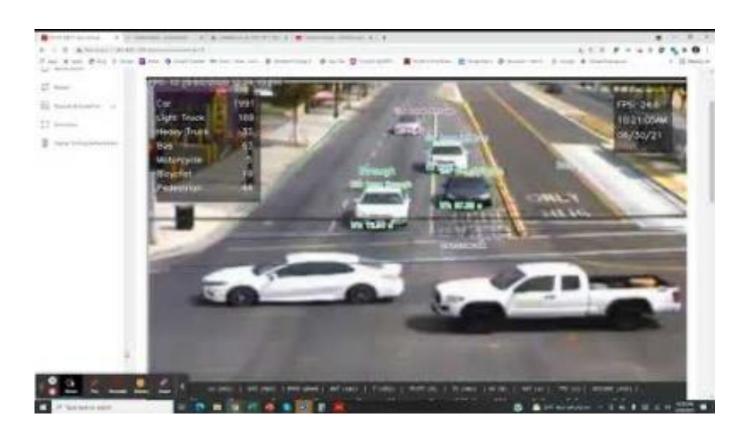


Optimization of Traffic / Safety Al models

System architecture overview



Works With Any Existing Camera System - Or New!









Functionality Overview



SDLC Detection

- Unlimited number of detection zones
- SDLC calls can be placed from inside the cabinet or remotely (via network switch)
- Accurate Vehicle, Ped and Bike detection



Advanced Traffic Analytics Reports

- Lane Occupancy (Queue Length)
- Counts with classification by size category
- Counts and Speed by lane
- Wait times
- Average speed by lane
- 85th Percentile speed by lane
- Passing time
- Free flow / passing time ratio
- Time gap
- Arrivals on Green
- Total Delay



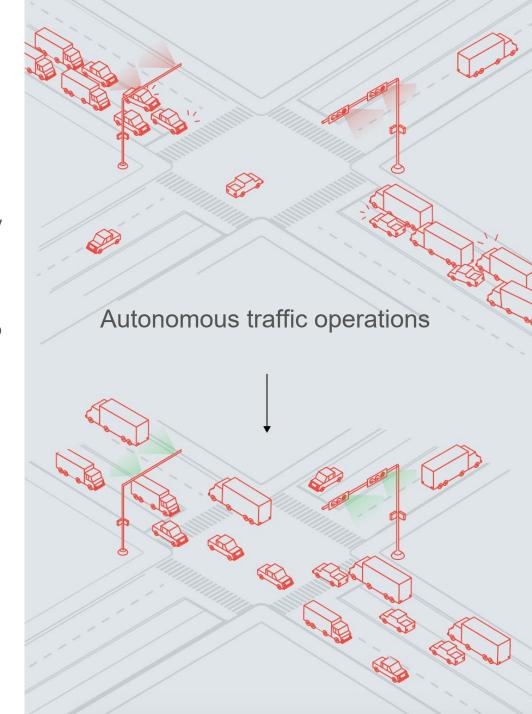
Real Time Notifications with Photo Evidence

- Wrong Way
- Slow and Stopped Traffic
- Stopped Car
- Pedestrian Detection
- Speeding
- Heavy Truck Alert
- Double Line Crossing
- Stop Sign Violation
- Red light Violation
- Near Misses
- False Detection Calls

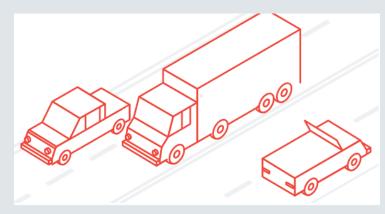
Intersection Adaptive / Green Utilization

CAPABILITIES OVERVIEW

- Single intersection and corridor level adaptive system using data collected by Currux Vision (queue length, delay times, counts, & speed)
- Model can be trained on data for the previous day /week / month
- Automatically calculates intersection split times in under 30 seconds to reduce the total delay at the Intersection
- 10 min to 4 hours split time table update
- Differentiates between week and weekend
- Weighting applied to various approaches
- System recommends the new split times or automatically upload the calculated split times to the controller using NTCIP
- System can automatically recalculate split times daily, weekly, monthly to capture the latest changes in traffic patterns and upload them to the controller.



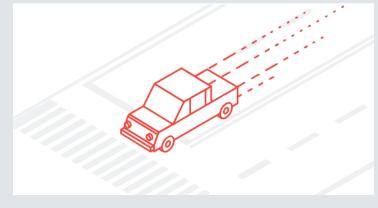
Standard Traffic Analytics Reports



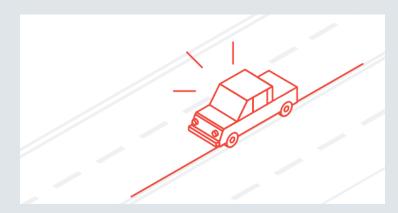
Vehicle counts by class, type, lane



Pedestrian and bicyclist counts

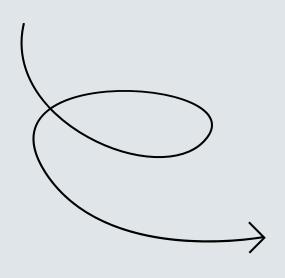


Average speed by lane



Event counts

- Vehicle counts by class, type, lane
- Pedestrian and bicyclist counts
- Average speed by lane
- Turn counts
- Event counts





Advanced Traffic Analytics

- Lane Occupancy (Queue Length)
- Average Speed
- 85th Percentile Speed
- Average Wait Time
- HWT Contact Car in Front
- Vehicle Counts
- Vehicle Stop Counts
- Passing Time
- Free Flow vs Sat Flow
- Gap Time
- Arrivals on Green
- Total Delay

Detailed Traffic Analytics By Lane and Approach

Lane	Lan	ne Average Occupancy (count)	Average Speed (mph)	85th Percentile Speed (mph)	Average Wait Time (sec)	HWT	ehicle Counts (cars)	Vehicle Stop Counts (cars)	Passing Time (sec)	Free Flow Time (sec)	FF/PT	Gap Time (sec)	AG (%)	Total Delay (sec)
Throug	gh	1.3	32	45	13	3.1	1243	110	471	456	96%	32.9	87	28
Left Turn		1	15	24	23	5.8	63	39	765	401	52%	361.1	17	387
Right		0	23	34	6	5.4	26	0	20388	8677	42%	1624.2	88	11717
						Show By	Time Table							
Lane	Start Time	Lane Average Occupancy (count)	y Average Speed (mph)	85th Percentile Spee (mph)	d Average Wait Tim (sec)	e HWT	Vehicle Counts (cars)	Vehicle Stop Counts (cars)	Passing Time (sec)	Free Flow Time (sec)	FF/PT	Gap Time (sec)	AG (%)	Total Delay (sec)
	00:00	0	31	40	15	15 5.8 22		1 571		557	97%	150.4	95	29
	01:00	0	32	32 39 0		0	7	0	0	0	0%	449.5	100	0
	02:00	0	39	48	0	0	11	0	0	0	0%	314	100	0
	03:00	1	32	46	12	0	11	1	11565	11562	99%	303.1	90	15
	04:00	0	37	37 44 0		5.4	13	0	0	0	0%	219.9	100	0
	05:00	1	37	49	12	1.8	44	1	3901	3899	99%	82.3	93	15
	06:00	1	36	45	12	3.5	83	1	4595	4588	99%	43	98	19
	07:00	1.3	35	45	14	3.8	182	8	473	439	92%	19.3	93	48
	08:00	1.3	33	43	12	3.3	231	10	406	369	90%	15.6	92	49
	09:00	1.3	31	45	12	3.1	230	27	156	141	90%	15.4	83	27
	10:00	1.5	30	45	14	2.9	302	50	93	86	92%	11.9	77	20
hrough	11:00	1.6	31	48	15	3	96	6	244	234	95%	11.9	90	25
illougii	12:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	13:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	14:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	15:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	16:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	17:00	0	0	0	0	0	0	0	0	0	0%	0	0	0
	18:00	0	0	0	0	0	0	0	0	0	0%	0	0	0

Queue length is calculated and displayed under Lane Occupancy = Cars Stopped

Turn Count Analytics



Vehicle counts by turn type and class



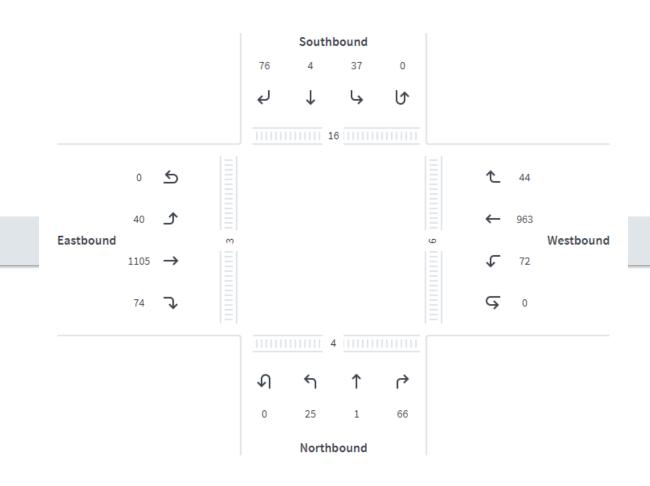
5 to 60 minutes time bins



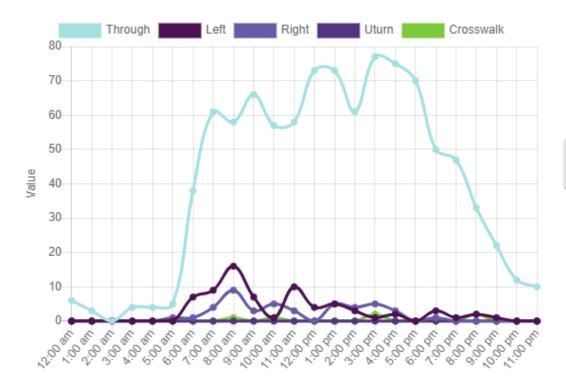
Ped and bike counts in crosswalk



PDF and Excel reports export



Turn Count Analytics



Time

Detailed Traffic Analytics By Turn Type and Approach

			Southbo	ound		Westbound						
Start Time	Through	Left	Right	Uturn	Crosswalk	Through	Left	Right	Uturn	Crosswalk		
12:00 am	0	1	0	0	0	6	0	0	0	0		
1:00 am	0	0	0	0	0	3	0	0	0	0		
2:00 am	0	0	0	0	0	0	0	0	0	0		
3:00 am	0	0	0	0	0	4	0	0	0	0		
4:00 am	0	0	0	0	0	4	0	0	0	0		
5:00 am	0	1	0	0	0	5	0	1	0	0		
6:00 am	0	0	0	0	1	38	7	1	0	0		
7:00 am	0	0	1	0	3	61	9	4	0	0		
8:00 am	0	0	2	0	0	58	16	9	0	1		
9:00 am	0	2	7	0	0	66	7	3	0	0		
10:00 am	0	4	6	0	0	57	1	5	0	1		
11:00 am	1	4	9	0	0	58	10	3	0	0		
12:00 pm	1	4	4	0	1	73	4	0	0	0		
1:00 pm	0	3	4	0	0	73	5	5	0	0		
2:00 pm	0	4	8	0	0	61	3	4	0	0		
3:00 pm	0	2	12	0	1	77	1	5	0	2		
4:00 pm	2	6	14	0	0	75	2	3	0	0		
5:00 pm	0	5	5	0	1	70	0	0	0	0		
6:00 pm	0	0	1	0	1	50	3	1	0	0		
7:00 pm	0	1	1	0	0	47	1	0	0	0		
8:00 pm	0	0	0	0	0	33	2	0	0	2		
9:00 pm	0	0	0	0	8	22	1	0	0	0		
10:00 pm	0	0	2	0	0	12	0	0	0	0		
11:00 pm	0	0	0	0	0	10	0	0	0	0		
Total	4	37	76	0	16	963	72	44	0	6		

Near Miss Trajectories Analytics / Report

Full trajectory based near miss analysis – Near Miss Trajectories – that will display the trajectories of objects with TTC below 1.5 seconds (or whatever the camera setting is)

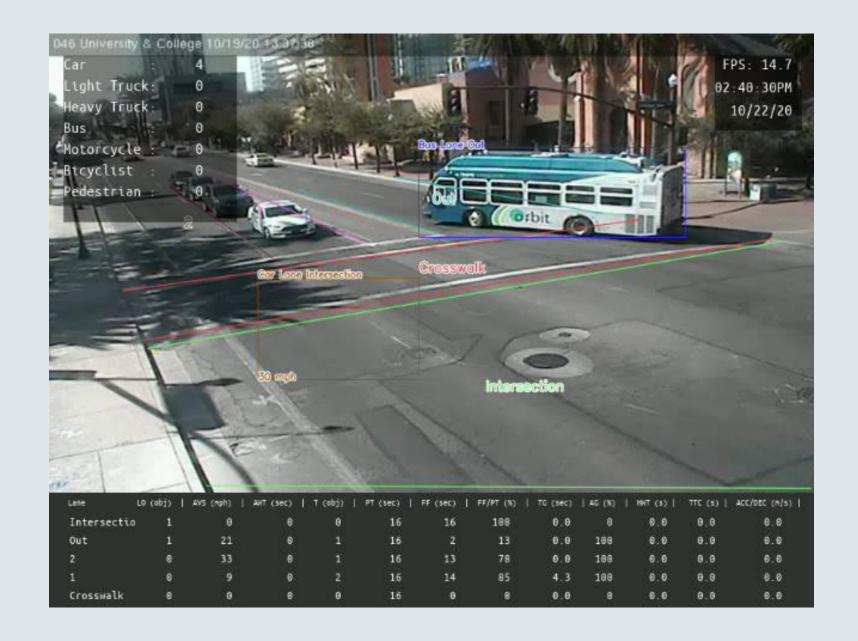


#	Lane	Number of Vehicles	Crosswalk Violations	Car Stopped at Intersection	HWT	Red Light Crossing	Near Misses	Lane Stopped	85th Percentile Speed(mph)	Speeding	% of Cars Speeding
1	Through	2146	0	0	2.8	0	0	0	44	200	0.09%
2	Left Turn	154	0	0	4.9	0	0	0	4	0	0%
3	Right Turn	50	0	0	4.7	0	0	0	32	0	0%

Pedestrian Detection and Tracking

Identifies and Track Pedestrians in Crosswalks

- Track in any direction
- Accurate Counts
- PED Speed
- Red Extension
- Passive PED Detection



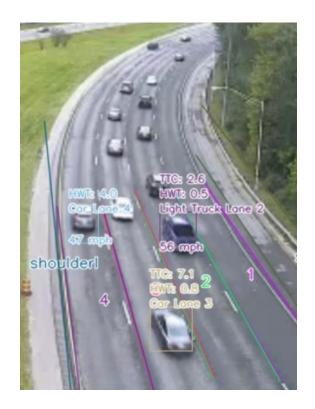
ITS Notifications Examples

Real-time notification examples

- Detection in inclement weather
- Speeding notification
- Stopped Lane
- Car Stopped



PED and Vehicle Violations



HWT: time it takes to hit car in front if that car stops immediately

TTC-time to collision if current speed of both cars is maintained







Illegal Pedestrian



Vehicle PED Violation

Stopped In Median







Stopped In Intersection

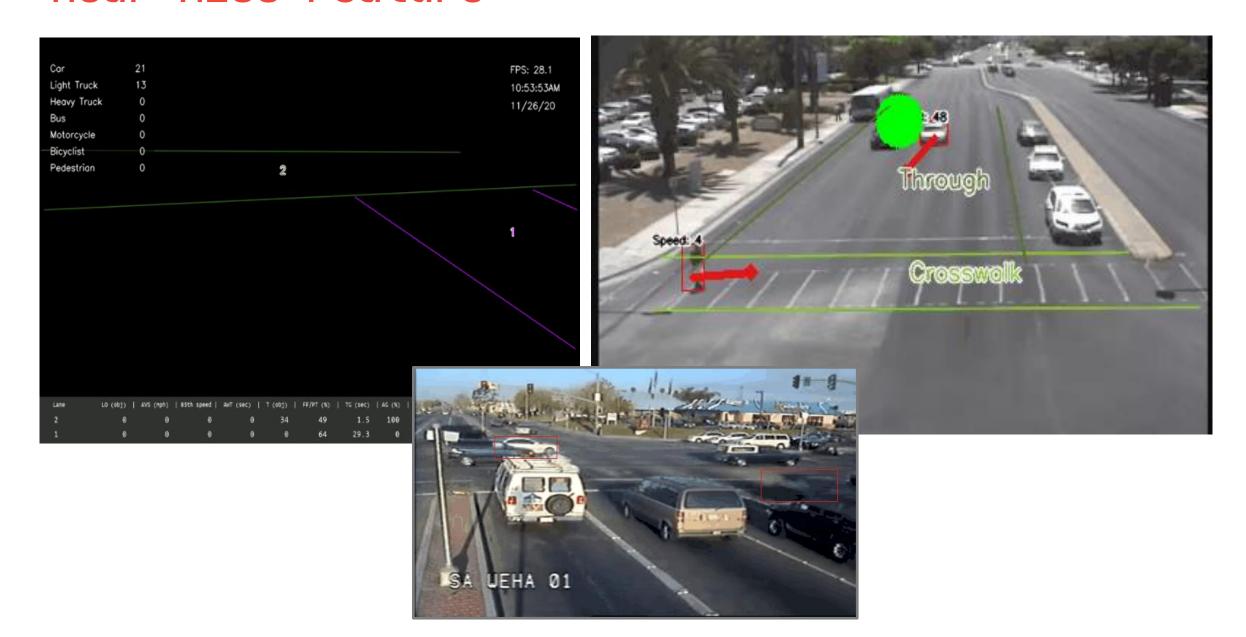


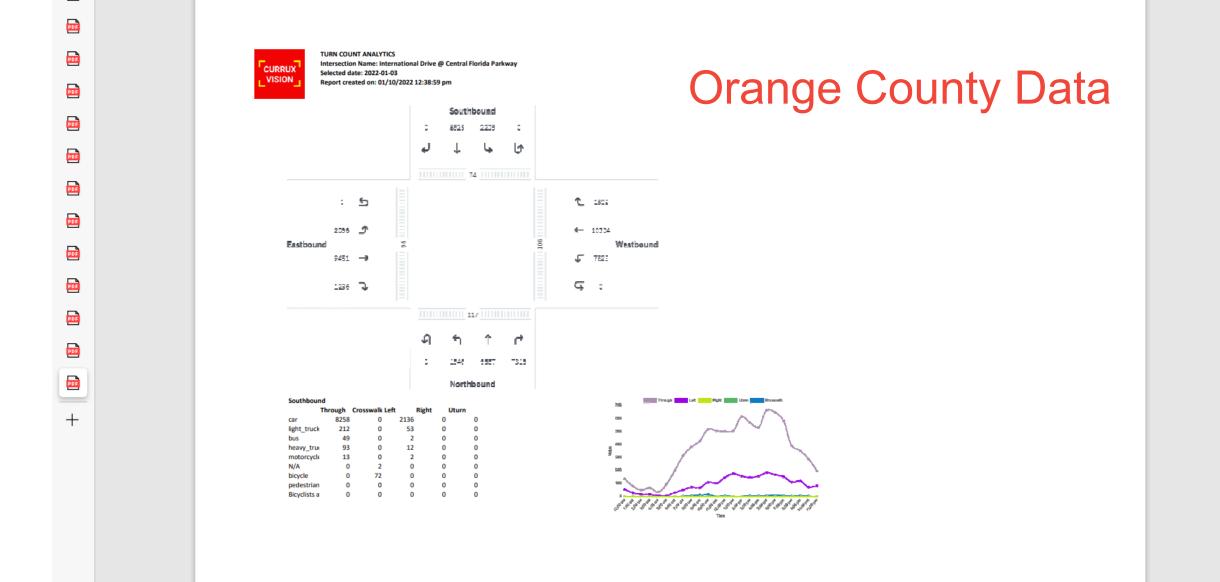
Vehicle PED Violation



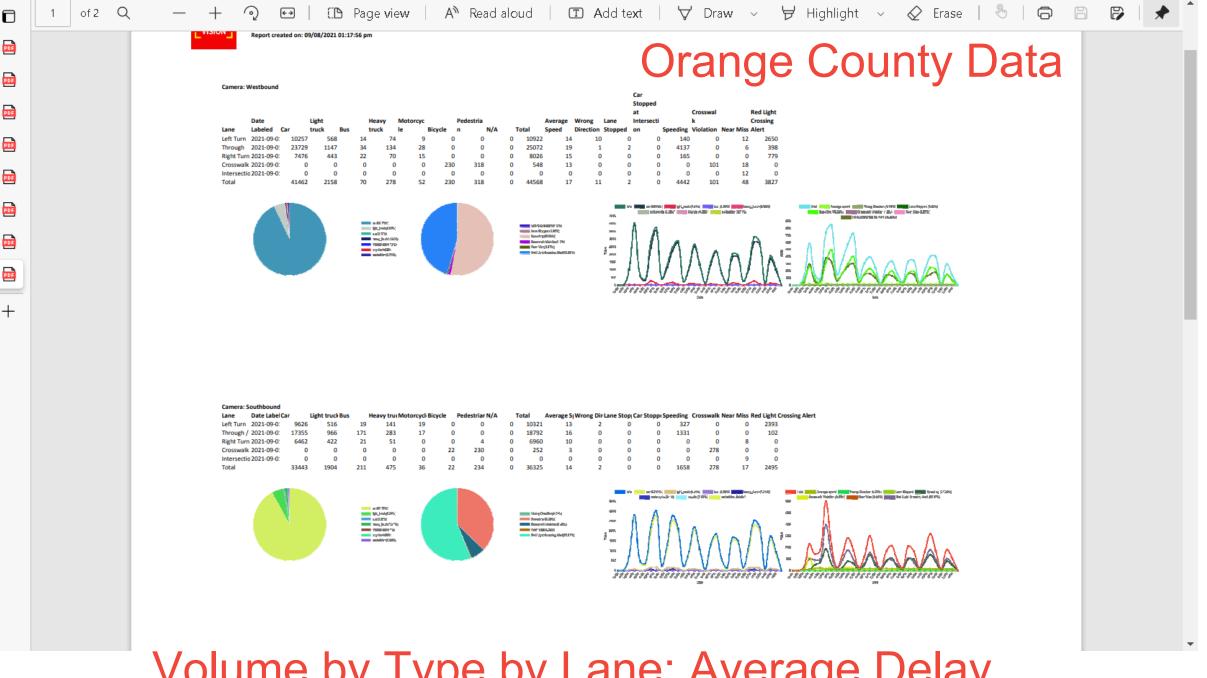
Wrong Way Detection

Near Miss Feature

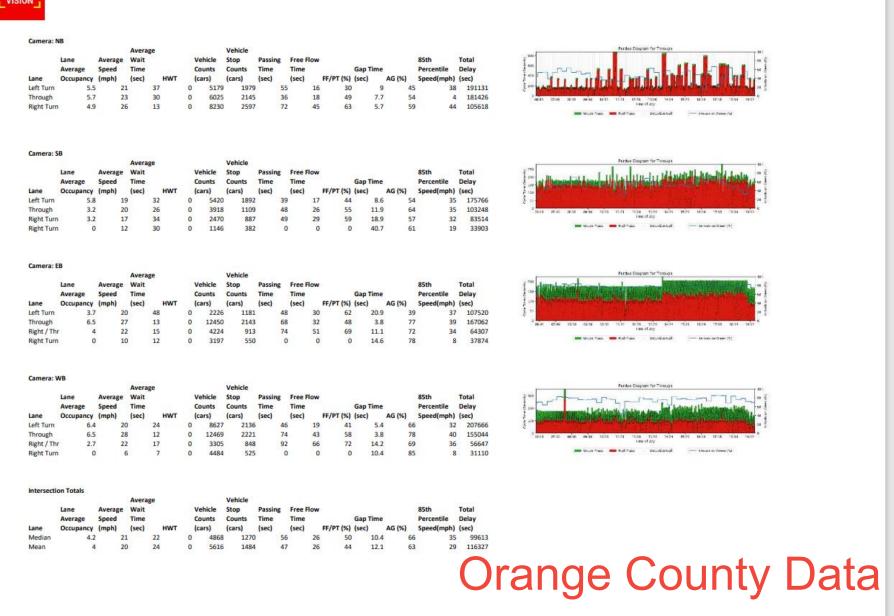




Turning Movement Counts



Volume by Type by Lane; Average Delay



Headway, 85th percentile, Total Delay



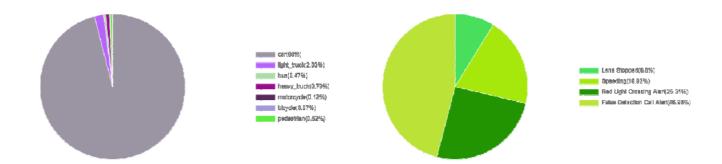
REPORT

Report Name: Standard Report

Selected date: 2021-11-26 00:00 - 2021-11-29 23:59 Report created on: 11/29/2021 10:59:50 am

Camera: NB Int Drive

Lane	Date Label Car		Light truck Bus		Heavy truc N	/lotorcycl Bi	cycle	Pe	edestrian N/A	Т	otal	Average Sp
Left Turn	2021-11-19	6577	188	64	70	3		0	0	0	6902	12
Through	2021-11-19	24630	432	164	149	40		0	0	0	25415	16
Right Turn	2021-11-19	24067	551	42	233	26		0	0	0	24919	16
Crosswalk	2021-11-19	0	0	0	0	0	3	9	299	0	338	5
Total		55274	1171	270	452	69	3	9	299	0	57574	15



Volume by Type by Lane; Average Speed by Lane



Existing Detection Auditing – Missed Call



Time: 09:11:13.216 Call is present but no object

Existing Detection Auditing – False Call



Red Light Runner



Signal timing adjustment recommendation based on real time Count Data

Questions?

CFMPOATSMO Network



Network



- Regional TSMO project impacts two contiguous cities/counties
- Set of integrated strategies to optimize the performance of operations on existing/new infrastructure

- Serves regional transportation needs such as access to and from the area outside the region
 - freight service and parking; evacuation; and security and privacy

Caveats



- Problem statement
- MPOs/TPOs may not have projects that meet the working definition
- TSMO is a dynamic discipline
- Low tech. to high tech.

Network



- Regional ITS Architecture
- Functional classification of roadways
- Arterials that cross jurisdictional lines
- Utilization thresholds for the non-SOV modes (transit routes, stops and stations, trails, bike/ped corridor usage)

Value Proposition



- Strengthening and guiding regional transportation operations collaboration and coordination
 - Vision and Direction
 - Commitment
 - Linkage: planning and operations

Examples



SR 40 Rural Signalized Intersections
 Collision Warning System (SR 40 through Volusia and Marion Counties)

 Beach Parking Information System (Flagler, Volusia, Brevard)

Next steps



- FDOT support
- Prioritization
- Advisory Team
- Coordination with FDOT D1

Thank You

MetroPlanOrlando.com | 407-481-5672 250 South Orange Ave., Suite 200, Orlando, FL 32801



Drone Workshop

Eric Hill, MetroPlan Orlando





Considerations and Applications for Integrating CAV into Complete Streets

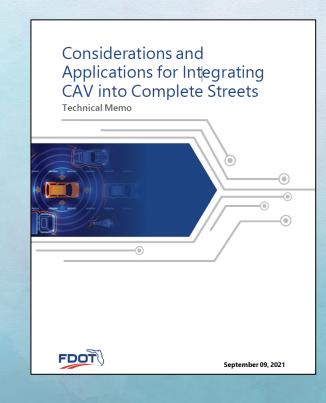
David Williams, VHB





Integrating CAV into Complete Streets

- Technical memo published by FDOT Central Office
- Two primary topics:
 - Complete Streets <u>Planning Considerations</u> for CAV
 - Applications of CAV technology to enhance
 Complete Streets
- Next Steps

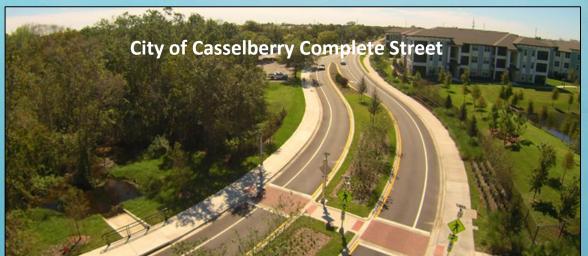






Integrating CAV into Complete Streets

- Complete Street prioritizes travel and safety for all users of the right-of-way, regardless of mode
 - Additional priority given to bike/ped and transit to operate safely
 - Dedicated zones for different modes,
 - Intersections and crossings that manage and prioritize all users, and
 - De-prioritization of vehicular traffic



Complete Streets Planning Considerations for CAV

- 1. Emerging modes of travel may affect Complete Streets
 - Automated transit
 - Terrestrial drones or Personal delivery devices (PDD)
 - Automated Mobility as a Service (MaaS)
 - Automated Micromobility (shared scooters, e-bikes, etc.)
 - Aerial Drones





Complete Streets Planning Considerations for CAV

2. Curb Management

 If automation leads a movement towards MaaS, curb management will continue to be an important element of any complete street policy

3. Impacts on Parking

- CAV may significantly affect parking demand
- Decreased parking demand may lead to opportunities for more productive land uses





Complete Streets Planning Considerations for CAV

4. Land Use Considerations

- Density
 - The more parking needed, the less building space available
 - Reduced parking demand may result in more productive, higherdensity land uses
- Sprawl
 - Lowered commuting cost (time + money) can increase commuters' willingness to travel further





Applications of CAV to enhance Complete Streets

Infrastructure-based Strategies

- Bike/Ped Detection
- Adaptive Signal Management Technologies
- Vehicle-to-Infrastructure (V2I) applications
- Multi-use slow travel lanes
- Dynamic/Managed Lanes
- Smart Work Zone
- Curb Management Technologies

3.1.1 Cyclist/pedestrian detection

Infrastructure that can actively monitor and detect the presence of cyclists, pedestrians and micromobility users, coordinate their travel with traffic signals at crossings, and alert drivers of their presence.

Benefits to complete streets: Understanding who is using the ROW will increase safety for all travelers and allow the management of vehicles and travelers within the ROW. This strategy will leverage other key CAV functions, such as ROW management, ROW allocation, and coordination with CV-enabled vehicles.

Current state of practice: Pedestrian and cyclist detection systems are being deployed today, including radar-based systems to detect the presence of objects within a specified area, and optical-based systems that utilize machine vision to detect the presence, position, and classification of objects in the ROW.

FDOT role: Funding, implementation (on appropriate FDOT facilities), standards, and guidance.

Requirements: System that can detect and classify ROW users by mode, placement, speed, and communication infrastructure between signals and/or other vehicles.

Applications of CAV to enhance Complete Streets

Vehicle-based Strategies

- CV Applications
- AV Transit
- Speed Management

Bike/Ped/Micro-based Strategies

- CV communications
- Automated Micromobility





Next Steps Beyond the White Paper

- 1. Identify crossovers between CAV and Complete Street programs
- 2. Develop CAV/Complete Streets toolbox for practitioners
- Conduct CAV/Complete Streets training webinar for FDOT staff and consultants
- 4. Identify opportunities for pilot project(s)





Questions / Comments?





Taking Time to FLEX – What's new in Training

David Williams, VHB





TSM&O Focused Learning Education and Experiences (FLEX)

- Types of training in FLEX Portal
 - TSM&O concepts
 - TSM&O applications
 - Field equipment
 - How-to training videos
- FLEX Portal is available with a free account



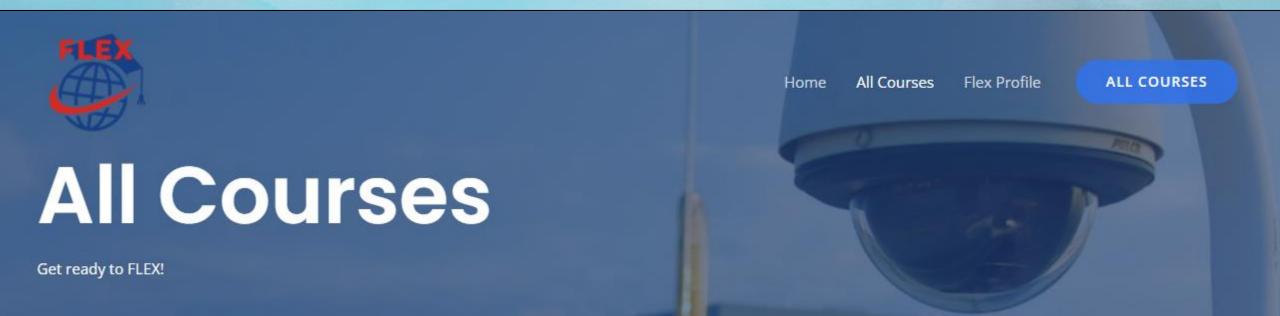


What's New?

Updated design



- New courses available
 - ITS Fiber Design
 - BlueToad/BlueARGUS Training
- RTMC Phone System
- RICMS Response Plan Training



TSM&O Focused Learning Education and Experiences (FLEX)

- Active Users 318
- Courses Completed 231
- Most Popular Course Traffic Signal Training (A)

- Troubleshooting Request Support button
- For more information, visit: https://elearning.cflsmartroads.com/
 - Google: "FDOT FLEX Portal"

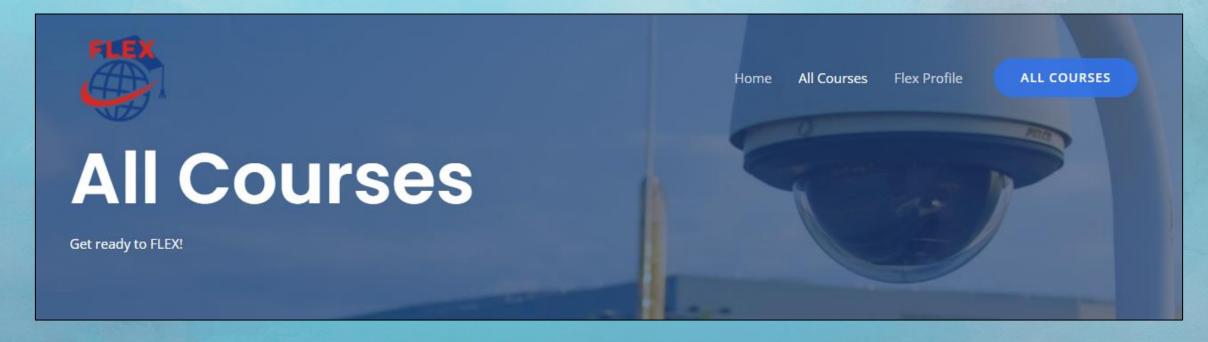




Courses Coming Soon to FLEX Portal



- Adaptive Signal Control Technology (ASCT) Training
- ITS CEI Dynamic Message Signs
- ITS CEI Road Weather Information System CBT
- Manual on Uniform Traffic Studies (MUTS)



Have a Suggested Training?



Don't see a course, webinar, or topic you are looking for...

Suggest it!

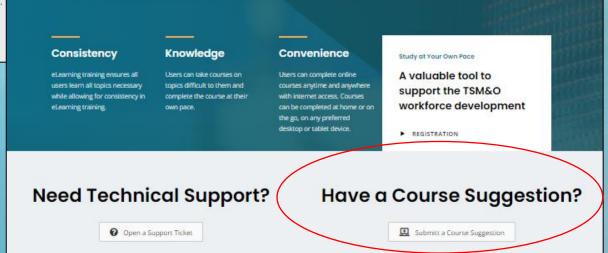
Transportation Systems Management and Operations (TSM&O) are planning processes and performance of existing multimodal infrastructure through the implementation of systems, preserve capacity and improve security, safety, and reliability of the transportation system. one-stop shop for all your on-demand training needs related to TSM&O!

https://elearning.cflsmartroads.com/flex-suggestions/





FLEX offers eLearning and blended learning courses to provide complete, flexible training solutions. Users are able to complete online training at their own pace, while individuals and organizations can overcome obstacles such as scheduling, reaching remote employees, and diverse learning styles.





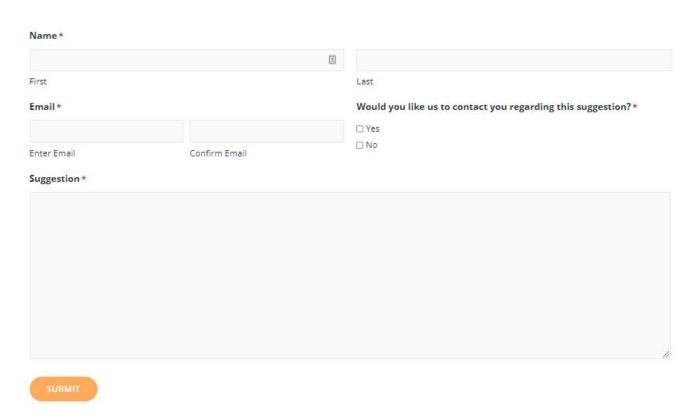
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Suggest it!

Get ready to FLEX!

https://elearning.cfls





plete, flexible training solutions. Users are able to rganizations can overcome obstacles such as Study at Your Own Pace A valuable tool to support the TSM&O workforce development a Course Suggestion? Submitt a Course Suggestion

ALL COURSES

STROZ Project Update

Jeremy Dilmore, District Five TSM&O





Signal Training for Regional Optimization Zone

- STROZ is a fully equipped training site located at the RTMC
- Purpose to provide a real-world scenario for training, demonstrations, and testing to occur
 - (without impacting real-world operations)
- The STROZ platform will enable FDOT to:
 - Host hands-on training for local agency staff (e.g., signal technicians)
 - Host vendors so they can demonstrate new technologies
 - Teach best practices for maintenance, repairs, and troubleshooting

Signal Training for Regional Optimization Zone

- Status
 - 90% of infrastructure is completed and installed,
 - concrete strain poles, span wire, signal heads, cabling, cabinet, and service pad
 - Remaining work includes installation of various roadside devices
 - Vehicle detection, Pedestrian detection, RSUs, BT readers, CCTV
 - Target Completion End of March 2022

Pictures



















Current Initiatives

Jeremy Dilmore, District Five TSM&O





THANK YOU!

Next Consortium - May 12, 2022







TSM&O Consortium Meeting

MEETING AGENDA

Teleconference or FDOT District 5 RTMC (4975 Wilson Rd, Sanford, FL 32771)

March 3, 2022 10:00 AM-12:00 PM

- 1) WELCOME
- 2) CURRUX VISION AI TAKEAWAYS
 - Hazem El Assar, Orange County Traffic Engineering
- 3) REGIONAL TSM&O PRIORITIZED PROJECTS
 - Eric Hill, MetroPlan Orlando
- 4) DRONE WORKSHOP
 - Eric Hill, MetroPlan Orlando
- INTEGRATING CAV INTO COMPLETE STREETS
 - David Williams, VHB
- 6) TAKING TIME TO FLEX WHAT'S NEW IN THE TRAINING PORTAL
 - David Williams, VHB
- 7) STROZ PROJECT UPDATE
 - Jeremy Dilmore, District Five TSM&O
- 8) CURRENT INITIATIVES
 - Jeremy Dilmore, District Five TSM&O